

Part 1

Introduction

Degenerate Diffusion and Free-boundaries

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- We will discuss, in these lectures, certain geometric and analytical aspects of **degenerate** and **singular** diffusion.
- Models of **degenerate diffusion** include the Porous medium equation, the Gauss curvature flow and the Harmonic mean curvature flow.
- Models of **singular diffusion** include the Curve shortening flow, the Ricci flow on surfaces and the Yamabe flow.
- Emphasis will be given to the **optimal regularity** of solutions to **degenerate diffusion** and **free-boundaries** via sharp a priori estimates, to the analysis of solutions to geometric flows near **singularities** and to the classification of **global solutions** (ancient or eternal).

The Heat Equation

The simplest model of diffusion is the familiar **heat equation**:

$$u_t = \Delta u, \quad (x, t) \in \Omega \times [0, T], \quad \Omega \subset \mathbb{R}^n$$

(u is the density of heat, chemical concentration etc.)

Fundamental properties of the Heat equation:

- **Smoothing Effect:** Solutions become instantly *smooth*, at time $t > 0$.
- **Infinite Speed of Propagation:** Solutions with non-negative compactly supported initial data $u(\cdot, 0)$, become instantly *strictly positive*, at time $t > 0$.
- **The Fundamental Solution:**

$$\Phi(x, t) = \frac{1}{(4\pi t)^{n/2}} e^{-\frac{|x|^2}{4t}}, \quad t > 0.$$

A basic model of non-linear diffusion

We consider the simplest model of **quasilinear diffusion**:

$$(*) \quad u_t = \Delta u^m = \operatorname{div}(m u^{m-1} \nabla u), \quad u \geq 0$$

for various values exponents $m \in \mathbb{R}$.

- **Porous medium equation** $m > 1$:

The diffusivity $D(u) = m u^{m-1} \downarrow 0$, as $u \downarrow 0$. (*) becomes **degenerate** at $u = 0$, resulting to finite speed of propagation (Slow diffusion).

- **Fast Diffusion** $0 \leq m < 1$:

The diffusivity $D(u) = m u^{m-1} \uparrow +\infty$, as $u \downarrow 0$. (*) becomes **singular** at $u = 0$, resulting to Fast diffusion.

- **Ultra-Fast Diffusion** $m < 0$:

When $m < 0$ we have ultra-fast diffusion with new interesting phenomena for example instant vanishing in some cases.

- Equation (*) appears in **many physical applications** and in **geometry** (Ricci flow on surfaces and Yamabe flow).

Contraction of hyper-surfaces by functions of their principal curvatures

Consider the evolution of a hyper-surface Σ^n in \mathbb{R}^{n+1} by the flow

$$\frac{\partial \mathbf{P}}{\partial t} = \sigma \mathbf{N}$$

where \mathbf{P} is the position vector, \mathbf{N} is a choice unit normal, and the speed σ is a smooth function of the principal curvatures λ_j of Σ .

Examples

- MCF: $\sigma = H = \lambda_1 + \dots + \lambda_n$
- IMCF: $\sigma = -\frac{1}{H} = -\frac{1}{\lambda_1 + \dots + \lambda_n}$
- GCF: $\sigma = K = \lambda_1 \cdots \lambda_n$
- GCF $^\alpha$: $\sigma = K^\alpha = (\lambda_1 \cdots \lambda_n)^\alpha, 0 < \alpha < \infty$.
- HMCF: $\sigma = \frac{1}{\lambda_1^{-1} + \dots + \lambda_n^{-1}}$.

Evolution Equations for Curvature flows

- CSF: Motion of a plane curve $y = u(x, t)$ by its **Curvature**

$$u_t = \frac{u_{xx}}{1 + u_x^2}.$$

- MCF: Motion of a surface $z = u(x, y, t)$ in \mathbb{R}^3 by its **Mean Curvature**

$$u_t = \frac{(1 + u_y^2)u_{xx} - 2u_x u_y u_{xy} + (1 + u_x^2)u_{yy}}{1 + |Du|^2}.$$

- GCF: Motion of a surface $y = u(x, y, t)$ in \mathbb{R}^3 by its **Gaussian Curvature**

$$u_t = \frac{\det D^2 u}{(1 + |Du|^2)^{3/2}}.$$

It resembles the evolution **Monge-Ampère** equation.

Evolution Equations for Curvature flows

- **HMCF**: Motion of a surface $y = u(x, y, t)$ in \mathbb{R}^3 by its **Harmonic Mean Curvature**

$$u_t = \frac{\det D^2 u}{(1 + u_y^2)u_{xx} - 2u_x u_y u_{xy} + (1 + u_x^2)u_{yy}}.$$

Remarks:

- The CSF and MCF are **strictly** parabolic and **quasi-linear**.
- The GCF and HMCF are **fully-nonlinear**.
- The GCF and HMCF are only **weakly** parabolic. They become **degenerate** (slow-diffusion) when the Gauss curvature $K = 0$.
- The HMCF becomes **singular** (fast-diffusion) as the mean curvature $H \rightarrow 0$.

The Questions - Motivation

These flows provide interesting models of **non-linear diffusion** where the interplay between analytical tools and geometric intuition lead to the development of new powerful techniques.

Many problems in **image analysis** use geometric flows: an image, represented by a gray-scale density function u , can be processed to remove noise by smoothing the level sets of u by a geometric flow.

Typical Questions

- Short and long time existence and regularity
- Free-boundaries
- Formation of singularities
- Classification of entire solutions (ancient or eternal)
- Existence through the singularities
- Final shape of the hyper-surface

Outline of lectures

- **Part 1: Degenerate Diffusion and Free-boundary Regularity**

We will discuss the **optimal regularity** of solutions to different models of degenerate diffusion equations.

After a brief discussion of the free-boundary regularity to the porous medium equation, we will discuss the regularity of **weakly convex** solutions to the Gauss curvature flow and the Harmonic mean curvature flow.

We will also discuss the **free-boundary regularity**.

- **Part 2: Singular Diffusion and Ancient solutions**

After a brief introduction to singular diffusion, we will discuss the existence, **uniqueness** and **singularity formation** in the Ricci flow on surfaces.

The last two lectures will be devoted on new results on **ancient** solutions of the the curve shortening flow, the Ricci flow of surfaces, the Yamabe flow.

The Porous Medium Equation

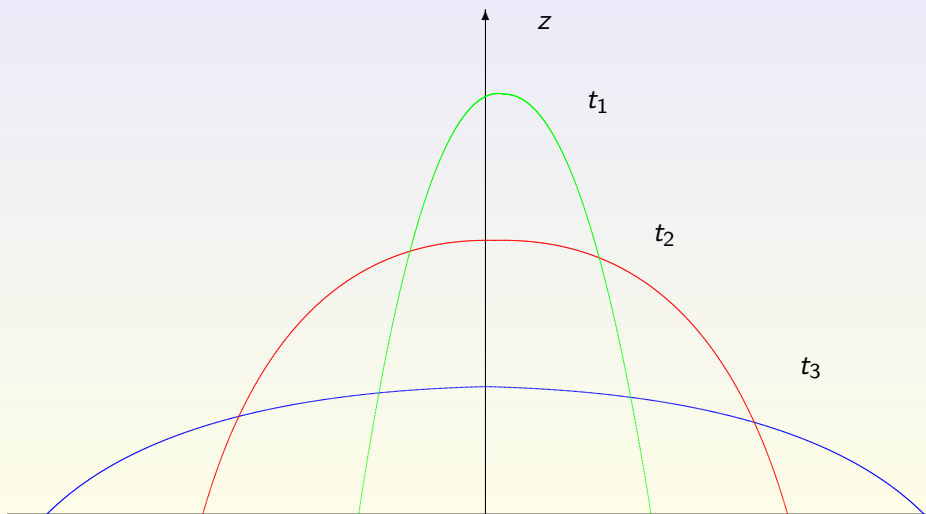
The simplest model of **non-linear degenerate diffusion** is the **porous medium equation**:

$$u_t = \Delta u^m = \operatorname{div} (m u^{m-1} \nabla u), \quad m > 1.$$

- It describes various diffusion processes, for example the flow of gas through a porous medium, where u is the **density** of the gas and $v := u^{m-1}$ is the **pressure** of the gas.
- Since, the diffusivity $D(u) = m u^{m-1} \downarrow 0$, as $u \downarrow 0$ the equation becomes **degenerate** at $u = 0$, resulting to the phenomenon of finite speed of propagation.
- **The Barenblatt solution**: $U(x, t) = t^{-\lambda} \left(C - k \frac{|x|^2}{t^{2\mu}} \right)_+^{\frac{1}{m-1}}$ with $\lambda, \mu, k > 0$. It plays the role of the **fundamental solution**.

The Barenblatt Solution

$$0 < t_1 < t_2 < t_3$$



Finite Speed of propagation

The Barenblatt solution shows that solutions to the p.m.e have the following properties:

- **Finite speed of propagation:** If the initial data u_0 has compact support, then the solution $u(\cdot, t)$ will have compact support at all times t .
- **Free-boundaries:** The interface $\Gamma = \partial(\overline{\text{supp}u})$ behaves like a free-boundary propagating with **finite speed**.
- **Solutions are not smooth:** Solutions with compact support are only of class C^α near the interface.
- **Weak solutions:** We say that $u \geq 0$ is a weak solution of the equation $u_t = \Delta u^m$ in $Q_T := \Omega \times (0, T)$, if it is continuous on Q_T and satisfies the equations in the distributional sense.

- Because it is **nonlinear**, the equation

$$(*) \quad u_t = \Delta u^m, \quad m \neq 1$$

has **rich scaling** properties.

- If u is a solution of $(*)$, then

$$v(x, t) := \frac{u(\alpha x, \beta t)}{\gamma}$$

is also a solution of (PM) if and only if

$$\gamma = \left(\frac{\alpha^2}{\beta}\right)^{1/(m-1)}.$$

The Aronson-Bénilan inequality

Aronson-Bénilan Inequality: Every solution u to the p.m.e. satisfies the differential inequality

$$(*) \quad u_t \geq -\frac{k u}{t}, \quad \lambda = \frac{1}{(m-1) + \frac{2}{n}}.$$

The *pressure* $v := \frac{m}{m-1} u^{m-1}$ which evolves by the equation

$$v_t = (m-1) v \Delta v + |\nabla v|^2$$

satisfies the **sharp** differential inequality

$$(**) \quad \Delta v \geq -\frac{\lambda}{t}.$$

Remark: The Aronson-Bénilan $(*)$ inequality follows from $(**)$. The differential inequality $(**)$ becomes an **equality** when v is the Barenblatt solution.

The Li-Yau type Harnack inequality

- The **Aronson-Bénilan** inequality $\Delta v \geq -\frac{\lambda}{t}$ and the equation for v imply the Li-Yau type differential inequality:

$$v_t + (m-1)\lambda \frac{v}{t} \geq |\nabla v|^2.$$

- Integrating this inequality on optimal paths gives the following **Harnack Inequality** due to **Auchmuty-Bao** and **Hamilton**:

$$v(x_1, t_1) \leq \left(\frac{t_2}{t_1}\right)^\mu \left[v(x_2, t_2) + \frac{\delta}{4} \frac{|x_2 - x_1|^2}{t_2^\delta - t_1^\delta} t_2^{-\mu} \right]$$

if $0 < t_1 < t_2$, with $0 < \mu, \lambda < 1$ and $\delta > 0$.

- **Application:** If $v(0, T) < \infty$, then for all $0 < t < T - \epsilon$ we have:

$$v(x, t) \leq t^{-\mu} (T^\mu v(0, T) + C(n, m, \epsilon) |x|^2)$$

i.e. the pressure v grows at most quadratically as $|x| \rightarrow \infty$.

The Cauchy problem with general initial data

Let $u \geq 0$ be a weak solution of $u_t = \Delta u^m$ on $\mathbb{R}^n \times (0, T]$.

- The **initial trace** μ_0 exists; there exists a Borel measure μ such that

$$\lim_{t \downarrow 0} u(\cdot, t) = \mu_0 \quad \text{in } D'(\mathbb{R}^n)$$

and satisfies the **growth condition**

$$(*) \quad \sup_{R>1} \frac{1}{R^{n+2/(m-1)}} \int_{|x|<R} d\mu_0 < \infty.$$

- The trace μ_0 determines the solution **uniquely**.
- For every measure μ_0 on \mathbb{R}^n satisfying $(*)$ there **exists** a continuous weak solution u of the p.m.e. with trace μ_0 .
- All solutions satisfy the **estimate** $u(x, t) \leq C_t(u) |x|^{2/(m-1)}$, as $|x| \rightarrow \infty$.

The regularity of solutions

- Assume that u is a continuous weak solution of equation

$$u_t = \Delta u^m, \quad m > 1 \quad \text{on } Q := B_\rho(x_0) \times (t_1, t_2).$$

- Remark:** It follows from **parabolic regularity** theory that if $u > 0$ in a parabolic domain Q , then $u \in C^\infty(Q)$.

Proof: If $0 < \lambda \leq u \leq \Lambda$ in Q , then $u_t = \operatorname{div}(m u^{m-1} \nabla u)$ is **strictly parabolic** with **bounded measurable** coefficients.

It follows from the *Krylov-Safonov* estimate that $u \in C^\gamma$, for some $\gamma > 0$, hence $D(u) := m u^{m-1} \in C^\alpha$.

We conclude that from the *Schauder estimate* that $u \in C^{2+\alpha}$ and by repeating then same estimate we obtain that $u \in C^\infty$.

The regularity of solutions

- **Question:** What is the optimal regularity of the solution u ?
- Caffarelli and Friedman: The solution u is of class C^α , for some $\alpha > 0$.
- This result is, in some sense, **optimal**: The **Barenblatt solution**
$$U(x, t) = t^{-\lambda} \left(C - k \frac{|x|^2}{t^{2\mu}} \right)_+^{\frac{1}{m-1}}$$
 with $\lambda, \mu, k > 0$ is only of class C^α near the interface $u = 0$.
- **Question:** Is it true that $u^{m-1} \in C^{0,1}$?

The regularity of the free-boundary

- Assume that the initial data u_0 has **compact support** and let u be the unique solution of

$$u_t = \Delta u^m \quad \text{in } \mathbb{R}^n \times (0, \infty), \quad u(\cdot, t) = u_0.$$

- **Question:** What is the **optimal regularity** of the free-boundary $\Gamma := \partial(\overline{\text{supp}u})$ and the solution u up to the free-boundary?
- Caffarelli-Friedman: The free-boundary is always C^α .
- Caffarelli-Vazquez-Wolanski: The free-boundary is of class $C^{1+\alpha}$, for $t \geq t_0$ with t_0 sufficiently large.
- D.-Hamilton: Under certain non-degeneracy conditions the free-boundary is C^∞ smooth for $0 < t < \tau_0$.
- Koch: The free-boundary is of class C^∞ , for $t \geq t_0$ with t_0 sufficiently large.

The equation for the pressure

Consider the **Cauchy problem** for the p.m.e:

$$\begin{cases} u_t = \Delta u^m & \text{in } \mathbb{R}^n \times (0, T) \\ u(\cdot, 0) = u_0 & \text{on } \mathbb{R}^n \end{cases}$$

with $u_0 \geq 0$ and **compactly** supported. It is more natural to consider the pressure $v = \frac{m}{m-1} u^{m-1}$ which satisfies

$$(*) \quad \begin{cases} v_t = (m-1)v \Delta v + |\nabla v|^2 & \text{in } \mathbb{R}^n \times (0, T) \\ v(\cdot, 0) = v_0 & \text{in } \mathbb{R}^n. \end{cases}$$

Our goal is to prove the **short time existence** of a solution v of $(*)$ which is C^∞ **smooth** up to the interface $\Gamma = \partial(\overline{\text{supp } v})$. In particular, the free-boundary Γ will be smooth.

Short time C^∞ regularity

Non-degeneracy Condition: We will assume that the initial pressure v_0 satisfies:

$$(**) \quad |\nabla v_0| \geq c_0 > 0, \quad \text{at } \overline{\text{supp} v_0}$$

which implies that the free-boundary will start moving at $t > 0$.

Theorem (Short time Regularity) (D., Hamilton)

Assume that at $t = 0$, the pressure $v_0 \in C_s^{2+\alpha}$ and satisfies (**). Then, there exists $\tau_0 > 0$ and a unique solution v of the Cauchy problem (*) on $\mathbb{R}^n \times [0, \tau_0]$ which is smooth up to the interface Γ . In particular, the interface Γ is smooth.

Remark: The space $C_s^{2+\alpha}$ is Hölder space for second derivatives that it is scaled with respect to an appropriate singular metric s . This is necessary because of the degeneracy of our equation.

Short time Regularity - Sketch of proof for dimension $n = 2$

- To simplify the notation we assume that we are in dimension $n = 2$.
- **Coordinate change**: We perform a change of coordinates which **fixes** the free-boundary: Let $P_0 \in \Gamma(t)$ s.t.

$$v_x > 0 \text{ and } v_y = 0, \quad \text{at } P_0.$$

Solve $z = v(x, y, t)$ near P_0 w.r to $x = h(z, y, t)$ to transform the **free-boundary** $v = 0$ into the **fixed boundary** $z = 0$.

- The function h evolves by the **quasi-linear**, degenerate equation

$$(\#) \quad h_t = (m - 1)z \left(\frac{1+h_y^2}{h_z^2} h_{zz} - \frac{2h_y}{h_z} h_{zy} + h_{yy} \right) - \frac{1+h_y^2}{h_z}$$

- **Outline**: Construct a sufficiently smooth solution of $(\#)$ via the **Inverse function Theorem** between appropriate Hölder spaces, scaled according to a **singular metric**.

The Model Equation

- Our problem is modeled on the equation

$$h_t = z (h_{zz} + h_{yy}) + \nu h_z, \quad \text{on } z > 0$$

with $\nu > 0$.

- The diffusion is governed by the **cycloidal metric**

$$ds^2 = \frac{dz^2 + dy^2}{z}, \quad \text{on } z > 0.$$

Its geodesics are **cycloid curves**.

- We define the **distance function** according to this metric:

$$\bar{s}((z_1, y_1), (z_2, y_2)) = \frac{|z_1 - z_2| + |y_1 - y_2|}{\sqrt{z_1} + \sqrt{z_2} + \sqrt{|y_1 - y_2|}}.$$

- The **parabolic distance** is defined as:

$$s((Q_1, t_1), (Q_2, t_2)) = \bar{s}(Q_1, Q_2) + \sqrt{|t_1 - t_2|}.$$

- Let C_s^α denote the space of Hölder continuous functions h with respect to the parabolic distance function s .
- $C_s^{2+\alpha} : h, h_t, h_z, h_y, z h_{zz}, z h_{zy}, z h_{yy} \in C_s^\alpha$.
- **Theorem** (Schauder Estimate) Assume that h solves

$$h_t = z(h_{zz} + h_{yy}) + \nu h_z + g, \quad \text{on } Q_2$$

with $\nu > 0$ and $Q_r = \{0 \leq z \leq r, |y| \leq r, t_0 - r \leq t \leq t_0\}$.
Then,

$$\|h\|_{C_s^{2+\alpha}(Q_1)} \leq C \{ \|h\|_{C_s^0(Q_2)} + \|g\|_{C_s^\alpha(Q_2)} \}.$$

Proof: We prove the Schauder estimate using the method of approximation by polynomials introduced by L. Caffarelli and I. Wang.

Short time regularity - summary

- Using the Schauder estimate, we construct a sufficiently smooth solution of (*) via the Inverse function Theorem between the Hölder spaces C_s^α and $C_s^{2+\alpha}$, which are scaled according to the **singular metric** s .
- Once we have a $C_s^{2+\alpha}$ solution we can show that the solution v is C^∞ **smooth**. Hence, the free-boundary $\Gamma \in C^\infty$.
- **Remark:** You actually need a **global** change of coordinates which transforms the free-boundary problem to a fixed boundary problem for a non-linear degenerate equation.

Long time regularity

- It is well known that the free-boundary will not remain smooth (in general) for all time. Advancing free-boundaries may hit each other creating **singularities**.
- Koch: (**Long time regularity**) Under certain natural initial conditions, the pressure v will become **smooth** up to the interface for $t \geq T_0$, with T_0 sufficiently large.
- **Question:** Under what **geometric conditions** the interface will become smooth and remain so at all time ?

Theorem (All time Regularity) (D., Hamilton and Lee)

If the initial pressure v_0 is **root concave**, then the pressure v will be smooth and root-concave at all times $t > 0$. In particular, the interface will remain **convex and smooth**.

The Gauss Curvature Flow

Consider the deformation of a convex compact surface Σ^n in \mathbb{R}^{n+1} by its **Gauss curvature** K :

$$\frac{\partial \mathbf{P}}{\partial t} = K \cdot \mathbf{N}, \quad K = \lambda_1 \cdots \lambda_n.$$

- **1974 Firey:** The GCF models the wearing process of tumbling stones subjected to collisions from all directions with uniform frequency. It shrinks strictly convex, *centrally symmetric* surfaces to **round** points.
- **Tso:** Existence and uniqueness for *strictly* convex and smooth initial data up to the time T when the surface Σ^n shrinks to a point.
- **Andrews:** *Firey's Conjecture:* the GCF shrinks strictly convex surfaces Σ^2 in \mathbb{R}^3 to **spherical** points.

The Regularity of solutions to GCF

If $z = u(x, t)$ defines Σ^n locally, then u evolves by the PDE

$$u_t = \frac{\det D^2 u}{(1 + |Du|^2)^{\frac{n+1}{2}}}.$$

A **strictly** convex surface evolving by the GCF remains strictly convex and hence **smooth** up to its collapsing time T .

The problem of the regularity of solutions in the **weakly** convex case is a difficult question. It is related to the regularity of solutions of the evolution **Monge-Ampère** equation

$$u_t = \det D^2 u.$$

Question: What is the optimal regularity of **weakly convex** solutions to the Gauss Curvature flow ?

The Regularity of solutions to GCF -Known Results

- **Hamilton:** Convex surfaces with **at most one** vanishing principal curvature, will instantly become strictly convex and hence smooth.
- **Chopp, Evans and Ishii:** If Σ^n is $C^{3,1}$ at a point P_0 and **two or more** principal curvatures **vanish at P_0** , then P_0 will not move for some time $\tau > 0$.
- **Andrews:** A surface Σ^2 in \mathbb{R}^3 evolving by the GCF is always $C^{1,1}$ on $0 < t < T$ and smooth on $t_0 \leq t < T$, for some $t_0 > 0$. This is the **optimal** regularity in dimension $n = 2$.
Remark: The regularity of solutions Σ^n in dimensions $n \geq 3$ poses a much harder question.
- **Hamilton:** If a surface Σ^2 in \mathbb{R}^3 has **flat sides**, then the flat sides will persist for some time.

Surfaces with Flat Sides

Consider a two-dimensional surface $\Sigma_t = (\Sigma_1)_t \cup (\Sigma_2)_t$ in \mathbb{R}^3 with $(\Sigma_1)_t$ **flat** and $(\Sigma_2)_t$ **strictly** convex.

- **Hamilton:** The flat side $(\Sigma_1)_t$ will shrink with *finite speed*.
- The curve $\Gamma_t = (\Sigma_1)_t \cap (\Sigma_2)_t$ behaves like a **free-boundary** propagating with finite speed. It will shrink to a point before the surface Σ_t does.
- Expressing the lower part of Σ_t as $z = u(x, y, t)$, we find the u evolves by

$$(*_1) \quad u_t = \frac{\det D^2 u}{(1 + |Du|^2)^{3/2}}$$

with $u = 0$, at $(\Sigma_1)_t$ and $u > 0$, on $(\Sigma_2)_t$.

- The equation becomes **degenerate** at $u = 0$.

Rotationally Symmetric Examples

- If $z = u(r, t)$ is a **rotationally symmetric** solution of the (GCF), then u satisfies by

$$u_t = \frac{u_r u_{rr}}{r(1 + u_r^2)^{\frac{3}{2}}}.$$

- **Model Equation** (near $r \sim 1$):

$$u_t = u_r u_{rr}.$$

- Specific solutions of the model equation:

$$\phi_1 = (r + 2t - 1)_+^2$$

and

$$\phi_2 = \frac{(r - 1)^3}{6(T - t)}.$$

- Conclusion: We expect that u **vanishes quadratically** at a moving the free-boundary.

The pressure function

- Since we expect quadratic behavior near $z = 0$ we introduce the pressure function $g = \sqrt{2u}$ and compute its evolution:

$$(*_2) \quad g_t = \frac{g \det D^2 g + g_\nu^2 g_{\tau\tau}}{(1 + g^2 |Dg|^2)^{3/2}}.$$

- $(*_2)$ is a **fully-nonlinear** equation which becomes degenerate at the boundary of the flat side $\Gamma_t = (\Sigma_1)_t \cap (\Sigma_2)_t$.
- We assume that the initial surface satisfies the **non-degeneracy** condition

$$(\#) \quad g_\nu = |Dg| \geq c_0 > 0 \text{ and } g_{\tau\tau} \geq c_0 > 0, \text{ at } \Gamma_0.$$

with $\nu =$ inner normal to Γ_0 and $\tau =$ tangential to Γ_0 .

GCF with flat sides - The Results

- **Short time Regularity (D., Hamilton):**

If at $t = 0$, $g = \sqrt{2u} \in C_s^{2+\alpha}$ and satisfies (#), then there exists $\tau_0 > 0$ for which the solution g to the GCF is smooth (up to the interface Γ_t) on $0 < t \leq \tau_0$. In particular, the free-boundary Γ_t is smooth.

- **Long time Regularity (D., Lee):**

The pressure g will remain smooth (up to the interface) up to the extinction time T_c of the flat side.

- **Regularity at the Extinction time (D., Lee):** At $t = T_c$ the surface Σ_t is at most of class $C^{2,\beta}$, $\beta < 1$.

Short time Existence - Outline of the proof

- **Pressure Equation:** We recall that the pressure p satisfies

$$(*2) \quad g_t = \frac{g \det D^2 g + g_\nu^2 g_{\tau\tau}}{(1 + g^2 |Dg|^2)^{3/2}}.$$

- **Coordinate change:** Let $P_0 \in \Gamma(t)$ s.t. $g_x > 0$ and $g_y = 0$ at P_0 . Solve $z = g(x, y, t)$ near P_0 w.r to $x = h(z, y, t)$ to transform the f.b. $g = 0$ into the **fixed** boundary $z = 0$.
- h evolves by the **fully-nonlinear degenerate** equation:

$$(*3) \quad h_t = \frac{-z \det D^2 h + h_z h_{yy}}{(z^2 + h_z^2 + z^2 h_y^2)^{3/2}}, \quad z > 0.$$

- **Outline:** We construct a sufficiently smooth solution of $(*3)$ via the Inverse Function Theorem between appropriate Hölder spaces, scaled according to a singular metric.

The Model Equation

- Our problem is modeled on the equation

$$h_t = z h_{zz} + h_{yy} + \nu h_z, \quad \text{on } z > 0$$

with $\nu > 0$.

- The diffusion is governed by the **singular metric**

$$ds^2 = \frac{dz^2}{z} + dy^2, \quad \text{on } z > 0$$

- We define the **distance function** according to this metric:

$$\bar{s}((z_1, y_1), (z_2, y_2)) = |\sqrt{z_1} - \sqrt{z_2}| + |y_1 - y_2|.$$

- The **parabolic distance** is defined as:

$$s((Q_1, t_1), (Q_2, t_2)) = \bar{s}(Q_1, Q_2) + \sqrt{|t_1 - t_2|}.$$

- Let C_s^α denote the space of Hölder continuous functions h with respect to the parabolic distance function s .
- $C_s^{2+\alpha} : h, h_t, h_z, h_y, z h_{zz}, \sqrt{z} h_{zy}, h_{yy} \in C_s^\alpha$.
- **Theorem** (Schauder Estimate) Assume that h solves

$$h_t = z h_{zz} + h_{yy} + \nu h_z + g, \quad \text{on } Q_2$$

with $\nu > 0$ and $Q_r = \{0 \leq z \leq r^2, |y| \leq r, t_0 - r^2 \leq t \leq t_0\}$.
Then,

$$\|h\|_{C_s^{2+\alpha}(Q_1)} \leq C \{ \|h\|_{C_s^0(Q_2)} + \|g\|_{C_s^\alpha(Q_2)} \}.$$

Proof: We prove the Schauder estimate using the method of approximation by polynomials introduced by L. Caffarelli and I. Wang.

Short time regularity - summary

- Using the Schauder estimate, we construct a sufficiently smooth solution of (*) via the Inverse function Theorem between the Hölder spaces C_s^α and $C_s^{2+\alpha}$, which are scaled according to the **singular metric** s .
- Once we have a $C_s^{2+\alpha}$ solution we can show that the solution v is C^∞ smooth. Hence, the free-boundary $\Gamma \in C^\infty$.
- **Observation:** To obtain the optimal regularity, degenerate equations need to be scaled according to the **right singular metric**.
- **Remark:** You actually need a **global** change of coordinates which transforms the free-boundary problem to a fixed boundary problem for a non-linear degenerate equation.

Regularity up to the extinction T_c of the flat side

- **Remark:** By the result of Andrews the surface will become **strictly convex** before it shrinks to a point.
- Let us denote by T_c the **extinction time** of the flat side.
- **The Result:** The solution g will remain **smooth** up to the interface on $0 < t < T_c$.
- **Main Step:** The solution g is of class $C_s^{1+\alpha}$.
- **Sketch of Proof:** We show that $h \in C_s^{1+\alpha}$: each derivative \tilde{h} of h satisfies a degenerate equation of the form

$$\tilde{h}_t = z a_{11} \tilde{h}_{zz} + 2\sqrt{z} a_{12} \tilde{h}_{zy} + a_{22} \tilde{h}_{yy} + b_1 \tilde{h}_z + b_2 \tilde{h}_y + H$$

with

$$a_{ij} = \begin{pmatrix} -h_{yy} & \sqrt{z} h_{zy} \\ \sqrt{z} h_{zy} & h_z - z h_{zz} \end{pmatrix}$$

and

$$b_1 = -\frac{h_{yy}}{h_z^3}.$$

I. A'priori Estimates

- 1 Ellipticity: $a_{ij}\xi_i\xi_j \geq \lambda|\xi|^2 > 0, \forall \xi \neq 0.$
- 2 L^∞ -Bound: $|a_{ij}| + |b_i| \leq \Lambda.$
- 3 Non-degeneracy: $b_1 \geq \nu > 0.$

Properties (1)-(3) follow from the next result which is shown by Pogorelov type computations.

- **Theorem (D., Lee)** Near $P_0 \in \Gamma_t$, where $g_x > 0$ and $g_y = 0$ we have:

$$0 < \lambda \leq \det a_{ij} \sim \frac{K}{g} \leq \frac{1}{\lambda}.$$

and

$$0 < \lambda \leq \operatorname{tr} a_{ij} \sim g_\nu^2 g_{\tau\tau} + g g_{\nu\nu} \leq \frac{1}{\lambda}.$$

- **Notation:**

$K =$ Gauss Curvature

$\nu =$ direction normal to the level sets of g

$\tau =$ direction tangential to the level sets of g .

II. Hölder Continuity of solutions to degenerate equations in non-divergence form

- **Theorem (D., Lee)** Let h be a classical solution of equation

$$h_t = za_{11}h_{zz} + 2\sqrt{z}a_{12}h_{zy} + a_{22}h_{yy} + b_1h_z + b_2h_y + H$$

on Q_2 . Assume that there exist constants λ and ν such that

$$a_{ij}\xi_j \geq \lambda|\xi|^2, \quad \forall \xi \in \mathbb{R}^2, \quad |a_{ij}| + |b_i| \leq \frac{1}{\lambda}, \quad \frac{b_1}{2a_{11}} \geq \nu.$$

Then, there exists $\alpha = \alpha(\lambda, \Lambda, \nu)$ such that

$$\|h\|_{C_s^\alpha(Q_1)} \leq C \{ \|h\|_{C^0(Q_2)} + \|H\|_{L_\sigma^3(Q_2)} \}$$

where $d\sigma = z^{\frac{\nu}{2}-1} dzdydt$ and

$$Q_r = \{0 \leq z \leq r^2, |y| \leq r, t_0 - r^2 \leq t \leq t_0\}.$$

- **Remark:** The above extends the Krylov-Safonov C^α -regularity result to the degenerate case.

Combining the a-priori estimates and the Hölder Regularity result, we conclude that:

- $h \in C_s^{1,\alpha} \Rightarrow g \in C_s^{1,\alpha}$.
- (Classical Regularity + Scaling) $\Rightarrow g \in C_s^{2+\alpha}$.
- (Local Estimates) $\Rightarrow g$ is C^∞ -up to interface Γ up to the extinction time T_c of the flat side.

Further regularity results in dimensions $n \geq 3$

Question: What is the **optimal regularity** of solutions to the GCF in dimensions $n \geq 3$?

- **Short time existence** of solutions Σ_t^n to the GCF with **flat sides** such that $\Sigma_t^n \in C^{1, \frac{2}{n}}$ for $0 < t < \tau_0$.
- **Long time regularity (Open Problem):** Is a surface Σ_t^n with flat sides going to remain of class $C^{1, \frac{n}{2}}$ until it becomes strictly convex ?
- **$C^{1, \alpha}$ -Regularity :** Are solutions of the GCF (or the evolution Monge-Ampère equation) always of class $C^{1, \alpha}$, for $\alpha > 0$?
- **Final Shape (Open Problem):** What is the final shape of the surface Σ_t^n as it shrinks to a point ? Does the surface become asymptotically **spherical** ?

Optimal regularity results in dimensions $n \geq 3$

Theorem : (D., Savin) Solutions to the GCF in dimension $n = 3$ are always of class $C^{1,\alpha}$.

Example: (D., Savin) In dimensions $n \geq 4$ there exist self-similar solutions of $u_t = \det D^2 u$ with edges persisting.

Theorem : (D., Savin) If the initial surface is of class $C^{1,\beta}$, then solutions Σ_t^n to the GCF for $n \geq 3$ are of class $C^{1,\alpha}$, for $0 < \alpha \leq \beta$.

Remark: Same results hold for motion by K^p , $p > 0$ and for viscosity solutions to

$$\lambda (\det D^2 u)^p \leq u_t \leq \Lambda (\det D^2 u)^p$$

for $0 < \lambda < \Lambda < \infty$ and $p > 0$.

Open Problem: Is a surface Σ_t^n with flat sides going to remain of class $C^{1,\frac{n}{2}}$ until it becomes strictly convex ?

The Q_k Curvature Flows

Consider a compact convex hypersurface Σ^n in \mathbb{R}^{n+1} evolving by the Q_k -flow for $1 \leq k \leq n$

$$\frac{\partial \mathbf{P}}{\partial t} = Q_k \mathbf{N}$$

with speed $Q_k(\lambda) = \frac{S_k(\lambda)}{S_{k-1}(\lambda)} = \frac{\sum \lambda_{i_1} \cdots \lambda_{i_k}}{\sum \lambda_{i_1} \cdots \lambda_{i_{k-1}}}$.

- $Q_1 = H$ (Mean Curvature)
- $Q_n = \frac{1}{\lambda_1^{-1} \cdots \lambda_n^{-1}}$ (Harmonic Mean Curvature)
- **Andrews:** Existence of **smooth** solutions with **strictly convex** and smooth initial data up to the time T when the surface shrinks to a point. The surface becomes **spherical** as $t \rightarrow T$.
- **Dieter:** Convex surfaces with $S_{k-1} > 0$ become instantly **smooth**.
- **Caputo, D., Sesum:** *Long time existence of $C^{1,1}$ convex solutions (not strictly convex).*

The Harmonic Mean Curvature Flow

Consider a compact surface Σ_t in \mathbb{R}^3 with flat sides evolving by the (HMCF)

$$\frac{\partial \mathbf{P}}{\partial t} = \kappa \cdot \mathbf{N}, \quad \kappa(\lambda_1, \lambda_2) = \frac{\lambda_1 \lambda_2}{\lambda_1 + \lambda_2} = \frac{K}{H}.$$

The resulting PDE is **fully-nonlinear**, weakly parabolic but becomes **degenerate** at points where $K = 0$ and **singular** when $H \rightarrow 0$. In the latter case the flow is not defined.

The **linearized operator** \mathcal{L} is given by

$$\mathcal{L} = a^{ik} \nabla_i \nabla_k u, \quad a^{ik} = \frac{\partial}{\partial h_k^j} \left(\frac{G}{H} \right).$$

Notice that in geodesic coordinates around a point at which the second fundamental form matrix $A = \text{diag}(\lambda_1, \lambda_2)$ we have

$$(a^{ik}) = \text{diag}\left(\frac{\lambda_2^2}{(\lambda_1 + \lambda_2)^2}, \frac{\lambda_1^2}{(\lambda_1 + \lambda_2)^2}\right)$$

Highly degenerate convex HMCF

Let $\Sigma_t = (\Sigma_1)_t \cup (\Sigma_2)_t$ in \mathbb{R}^3 with $(\Sigma_1)_t$ **flat** and $(\Sigma_2)_t$ **strictly convex**. Let $\Gamma_t = (\Sigma_1)_t \cap (\Sigma_2)_t$ denote the interface.

Expressing the lower part of Σ as a graph $z = u(x, y, t)$, we find that u evolves by:

$$u_t = \frac{\det D^2 u}{(1 + u_x^2)u_{yy} - 2u_x u_y u_{xy} + (1 + u_y^2)u_{xx}}.$$

Theorem: (D., Caputo:) If Σ_0 is of class $C^{k,\alpha}$, $k \geq 1$, $0 < \alpha \leq 1$ then: the HMCF admits a viscosity solution of class $C^{k,\alpha}$ with pressure **smooth** up to the *interface* $\Gamma_t = (\Sigma_1)_t \cap (\Sigma_2)_t$.

The flat side persists for some positive time and the **interface** Γ_t is smooth and evolves by the **Curve Shortening Flow**.

The Q_k -flow in $\dim n \geq 3$

In the case of a convex surface Σ^n in \mathbb{R}^{n+1} with **flat sides** evolving by the Q_k -flow

$$\frac{\partial \mathbf{P}}{\partial t} = Q_k \cdot \mathbf{N}, \quad Q_k = \frac{S_k(\lambda)}{S_{k-1}(\lambda)}$$

then a similar result was recently shown:

- **Caputo, D., Sesum.** *Short time existence* of a solution with flat sides which is **smooth** up to the interface. In particular, the interface moves by the $n - 1$ dimensional Q_{k-1} flow.
- **Caputo, D., Sesum:** *Long time existence* of $C^{1,1}$ **convex** solutions (not strictly convex).

Question: What is the **optimal regularity** of solutions ?

Question: Do solutions become **strictly convex** before they shrink to a point ?

HMCF on star-shaped surfaces with $H > 0$

We assume that the initial surface Σ_0 is compact, **star-shaped**, of class $C^{2,1}$, and has **strictly positive** mean curvature $H > 0$.

Jointly with **Natasa Sesum**:

- **Short time existence:** There exists $\tau > 0$, for which the HMCF admits a $C^{2,1}$ solution Σ_t , such that $H > 0$ on $t \in [0, \tau)$.
- **Long time existence:** Let $T = A/4\pi$, with A the initial surface area. Then one of the following holds:
 - (i) $H \rightarrow 0$ at some point $P_0 \in \Sigma_{t_0}$, at time $t_0 < T$, **or**
 - (ii) a $C^{1,1}$ solution to the flow exists up to T , it becomes **strictly convex** at time $T_c < T$, and it shrinks to a **point** at time T .
- **Question:** Does $H \rightarrow 0$ before the time T ?
- On a **surface of revolution** with $H > 0$, we have $H > 0$ up to $T = A/4\pi$. Hence, Σ_t exists up to T and shrinks to a point at T . Moreover, $\Sigma_t \in C^\infty$, $0 < t < T$.
- **Open problem:** Higher dimensions.

Closing Remarks

- Degenerate equations with certain structure have **smoothing** properties once their solutions are scaled with respect to the appropriate singular metric.

As a result, one may obtain the C^∞ -regularity in a number of degenerate free-boundary problems related to curvature flows.

- In other cases the solutions do not become regular and one needs to develop more sophisticated techniques to establish the **optimal regularity** of solutions or pass through their singularities.

Open Problem: Find a flow which will take a non-convex surface with certain geometric properties and deform it to a smooth convex surface.